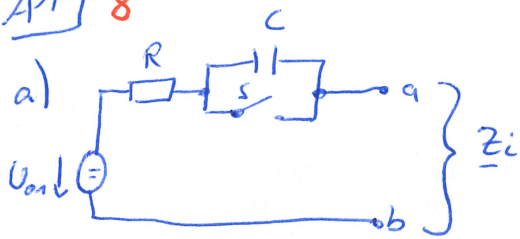


Musterlösung

A1 8



$$R_{Ges} = \frac{(R_1+R_2)(R_3+R_4)}{(R_1+R_2)+(R_3+R_4)} = \frac{4R^2}{4R} = R \quad 3$$

b)

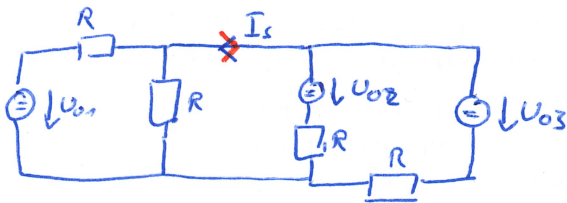
$$Z_i^+ = R + \frac{1}{j\omega C} = R - j\frac{1}{\omega C} \quad ; \quad Z_i^- = R \quad 2$$

c)

$$I_k^- = \frac{U_{01}}{Z_i^-} = \frac{4V}{R} \quad (\Rightarrow) \quad R = \frac{U_{01}}{I_k^-} = \frac{4V}{0,2A} = 20\Omega \quad 3$$

A2

a)



$$U_{02} = R_i \cdot I_{02} = \frac{R}{2} \cdot I_{02} \quad 2$$

b) 1



Graph  
Baum

c) 1

$$m = z - k + 1 = 6 - 4 + 1 = 3$$

d) 1

$$\begin{pmatrix} 2R & R & 0 \\ R & 2R & R \\ 0 & R & 2R \end{pmatrix} \begin{pmatrix} \dot{I}_1 \\ \dot{I}_2 \\ \dot{I}_3 \end{pmatrix} = \begin{pmatrix} U_{01} \\ U_{02} \\ U_{02} - U_{03} \end{pmatrix}$$

e) 2

$$\begin{aligned} \text{I. } & 2R \cdot \dot{I}_1 + R \cdot \dot{I}_2 = U_{01} \\ \text{II. } & R \cdot \dot{I}_1 + 2R \cdot \dot{I}_2 + R \cdot \dot{I}_3 = U_{02} \\ \text{III. } & R \cdot \dot{I}_2 + 2R \cdot \dot{I}_3 = U_{02} - U_{03} = 0 \end{aligned}$$

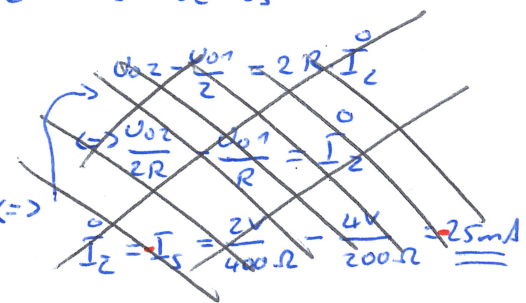
$$\boxed{I_3 = -I_2}$$

$$\text{I. } \dot{I}_1 = \frac{U_{01} - R \cdot \dot{I}_2}{2R} \quad ; \quad \text{III. } \dot{I}_3 = -\frac{\dot{I}_2}{2}$$

In II einsetzen:

$$R \cdot \frac{U_{01} - R \cdot \dot{I}_2}{2R} + 2R \cdot \dot{I}_2 + R \cdot \frac{\dot{I}_2}{2} = U_{02} = \frac{U_{01}}{2} - \frac{R}{2} \cdot \dot{I}_2 + 2R \cdot \dot{I}_2 + \frac{R}{2} \cdot \dot{I}_2 \quad (\Rightarrow)$$

$$\frac{U_{01}}{2} - \frac{R}{2} \cdot \dot{I}_2 + 2R \cdot \dot{I}_2 - \frac{R}{2} \cdot \dot{I}_2 = U_{02} = \frac{U_{01}}{2} + R \cdot \dot{I}_2 \quad (\Rightarrow) \quad \dot{I}_2 = \frac{U_{02} - \frac{U_{01}}{2}}{R} = 0,1$$



A3]

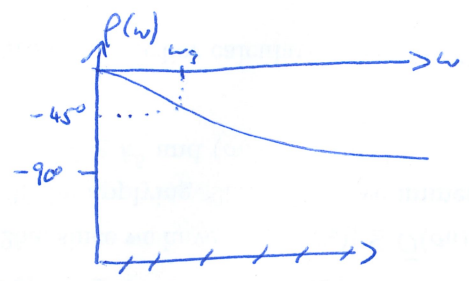
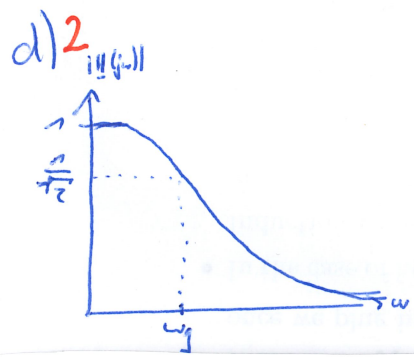
a)  $H(j\omega) = \frac{1}{\frac{1}{j\omega C} + 2R} = \frac{1}{2R + \frac{1}{j\omega C}} = \frac{1}{1 + j\omega 4CR}$  1

b)  $|H(j\omega)| = \frac{1}{\sqrt{1 + 16\omega^2 C^2 R^2}}$  ;  $\phi(\omega) = -\arctan(4\omega CR)$  2

c) 2

	$ H(j\omega) $	$\phi(\omega)$
$\omega=0$	1	0
$\omega \rightarrow \infty$	0	-90°

$|H(j\omega_g)| = \frac{H_{max}}{\sqrt{2}} = \frac{1}{\sqrt{1 + 16\omega_g^2 C^2 R^2}} \quad | \quad H_{max} = 1$   
 $\Rightarrow 1 = 16\omega_g^2 C^2 R^2 \Leftrightarrow \omega_g = \frac{1}{4CR}$   
 $\phi(\omega_g) = -45^\circ$



e) Tiefpassverhalten 1

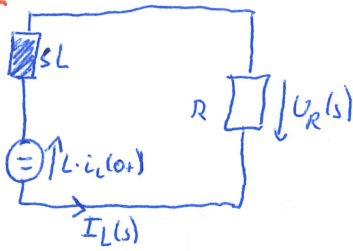
f)  $Z_i = R + \frac{2R \cdot \frac{1}{j\omega C}}{2R + \frac{1}{j\omega C}}$   
 $= R + \frac{R}{\frac{2R + \frac{1}{j\omega C}}{j\omega C}} = R + \frac{R}{j\omega 4CR + 1}$   
 $= R + \frac{j\omega C 4R^2 + R}{1 + \omega^2 16\omega^2 C^2 R^2}$

g)  $Z_{last} = Z_i^* = R + \frac{R}{1 + \omega^2 16\omega^2 C^2 R^2} - j \frac{\omega C 4R^2}{1 + \omega^2 16\omega^2 C^2 R^2}$

A4|

a)  $i_L(t=0^-) = i_L(t=0^+) = \frac{U_0}{R}$  ✓

b) 2



c) 1

$$I_L(s) = \frac{L \cdot i_L(0^+)}{sL + R} = \frac{L \cdot U_0}{sLR + R^2} = \frac{U_0}{R} \cdot \frac{1}{s + \frac{R}{L}}$$

d) 2

$$U_R(s) = -R \cdot I_L(s) = -U_0 \cdot \frac{1}{s + \frac{R}{L}}$$

$$u_R(t) = -U_0 \cdot e^{-\frac{R}{L} \cdot t}$$

e) 1

